







A Soft and Robust Electroadhesive Device

YANZHOU FU, SHUYUAN WANG, DONGLIANG FAN, and HONGQIANG WANG

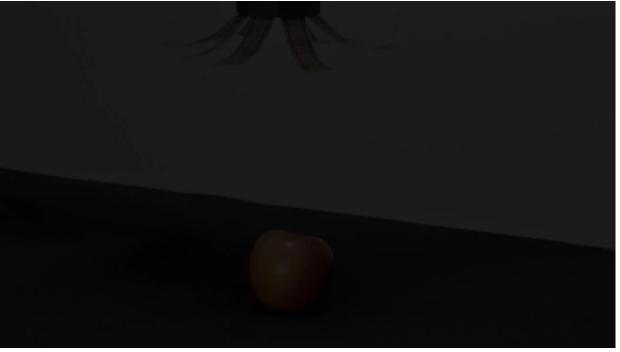
The Department of Mechanical and Energy Engineering,

Southern University of Science and Technology, Shenzhen 518055, Guangdong, China.

Corresponding author: wanghq6@sustech.edu.cn

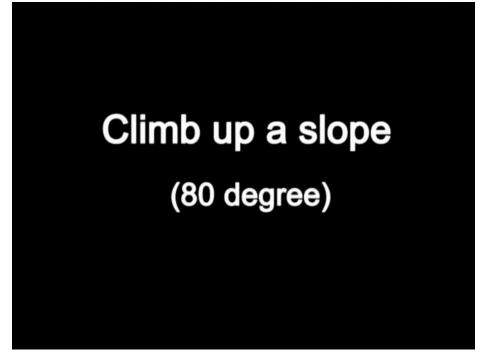


Motivation





Advanced Actuators & Robotics Lab



[GRABIT]

[Advanced Actuators & Robotics Lab, SUSTech]

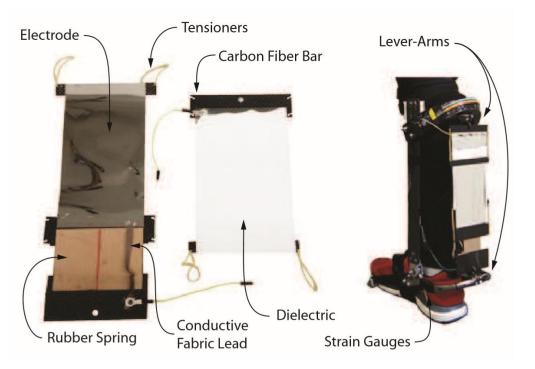
Extensive applications:

- grippers
- wall climbing robots
- clutches

Motivation

Extensive applications:

- suction grippers
- wall climbing robots
- clutches





Advantages:

- ✓ light weight
- ✓ strong force
- ✓ quick response



SUSTECH Southern University of Science and Technology Principle Advanced Actuators & Robotics Lab high voltage on electrode attract free charges in conductors induced and polarized charges polarization in insulating objects object air gap electrodes insulation substrate

Challenges substrate breakdown electrode



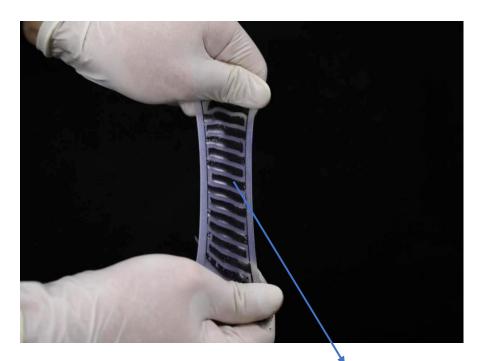
- thin metal foils
- insulation cover layers

Disadvantages:

- χ can not adhere to complex shapes
- $\boldsymbol{\chi}$ susceptible to electrical breakdown

Proposal





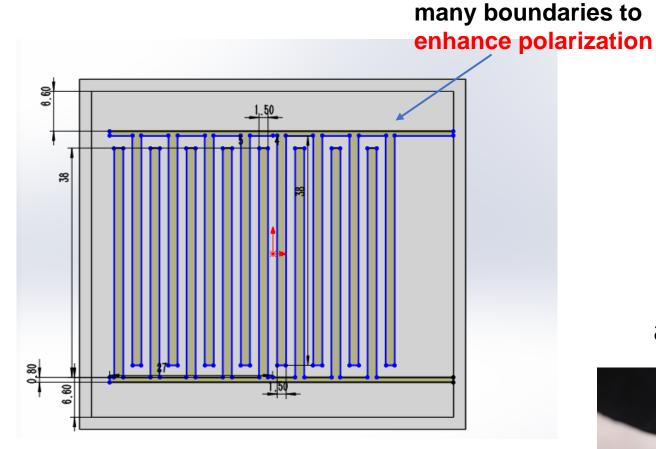
(previous) metal foils \longrightarrow conductive fluid

conductive fluid (carbon nanotube suspension)

(previous) soft elastomer stiff plastics-(Ecoflex 00-30, Smooth-On)

Advantages:

- ✓ highly soft, deformable and adaptive
- ✓ self-healing of circuit, robust

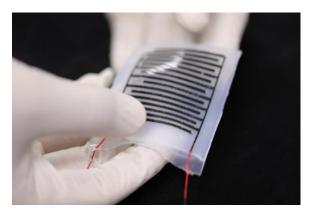


Standard Interdigitated Electrode Plate



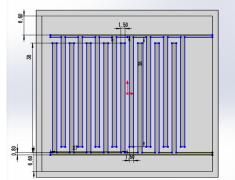
length	38 mm
width	1.5 mm
height	0.5 mm
spacing	1.5 mm

Effective electrostatic adhesion area is 9 cm².

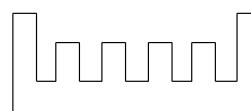


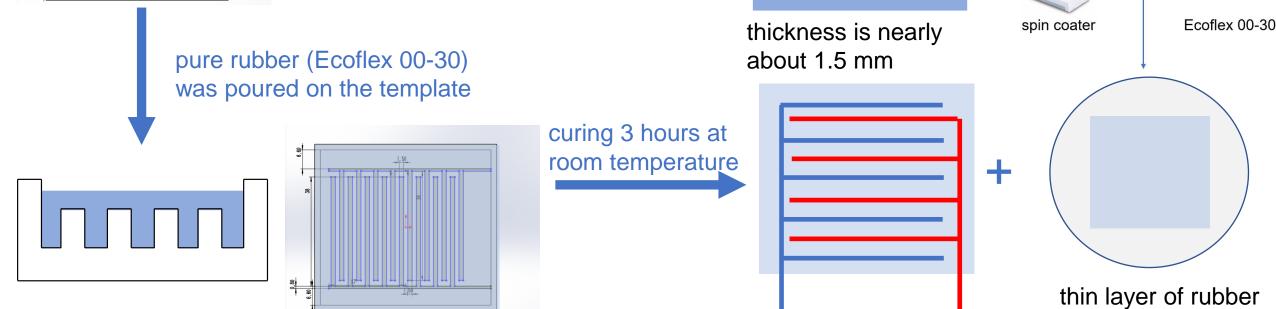


3D printing technology



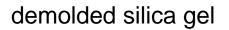
two-row positive and negative interdigital electrode template



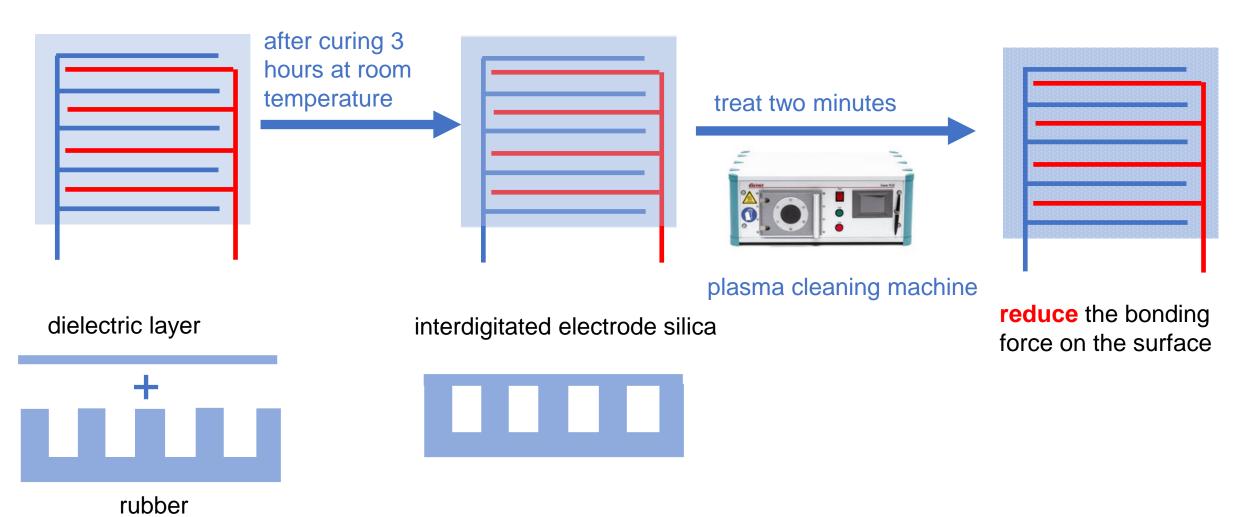




different spin speed

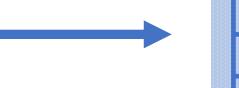


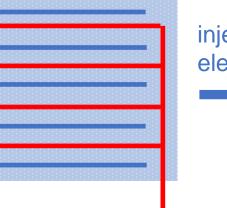






after curing 3 hours at room temperature



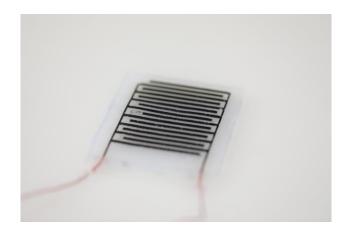


well bonded

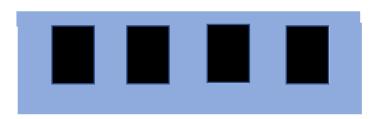
injected into the interdigitated electrode microchannel



carbon nanotube suspension

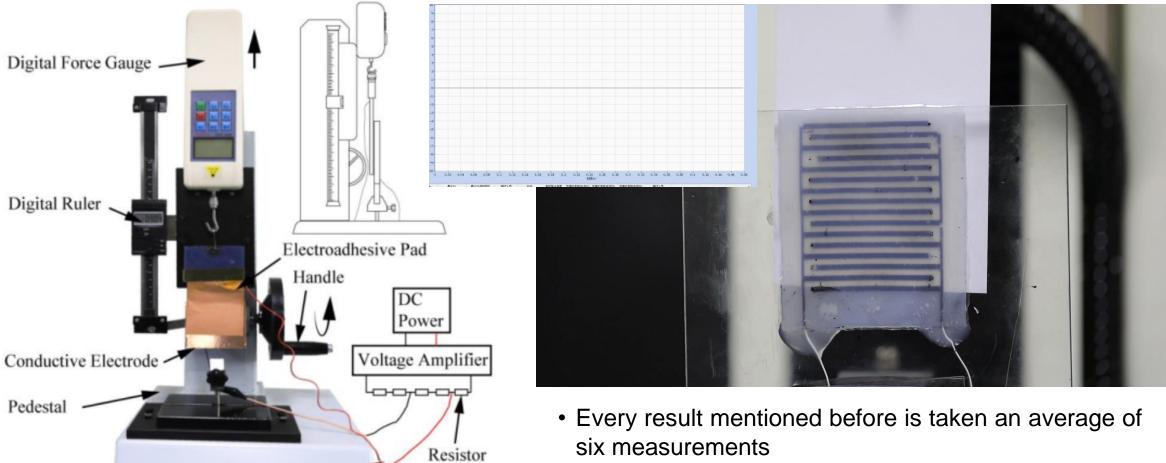


sealed after two wires are respectively connected

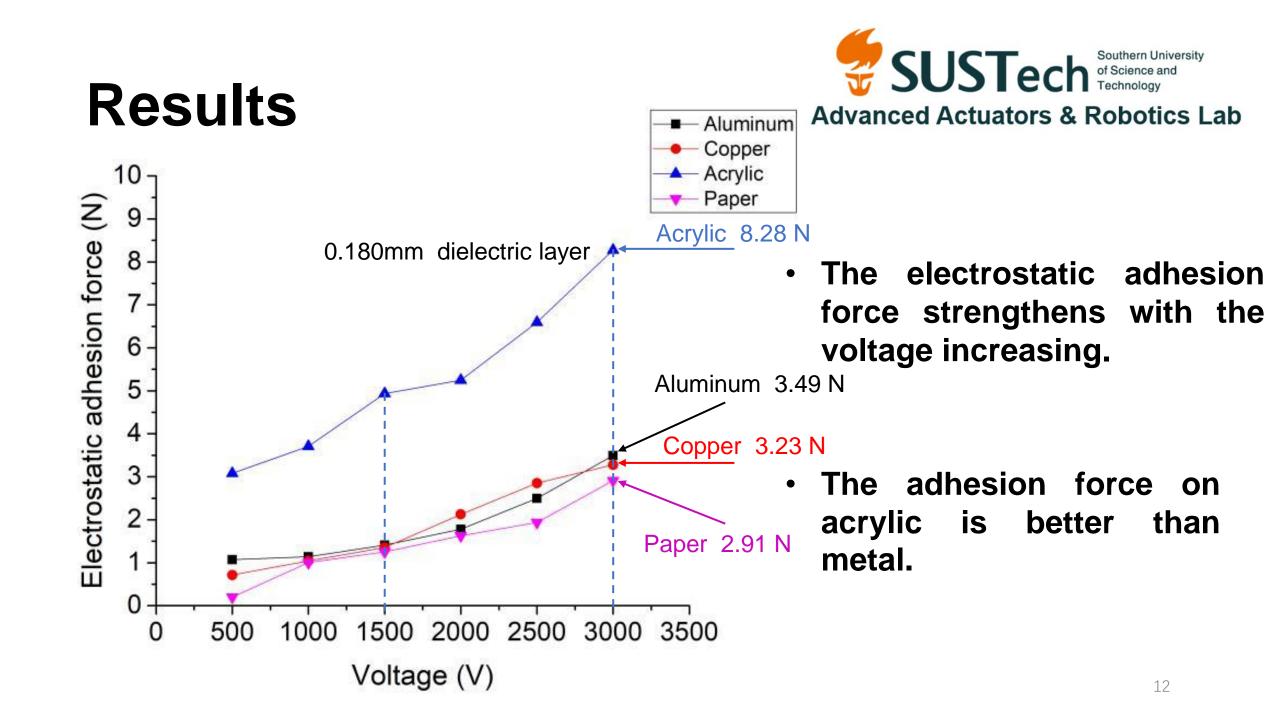




Experimental process



• Each test has half an hour interval (in order to **remove remnant polarized charges**).



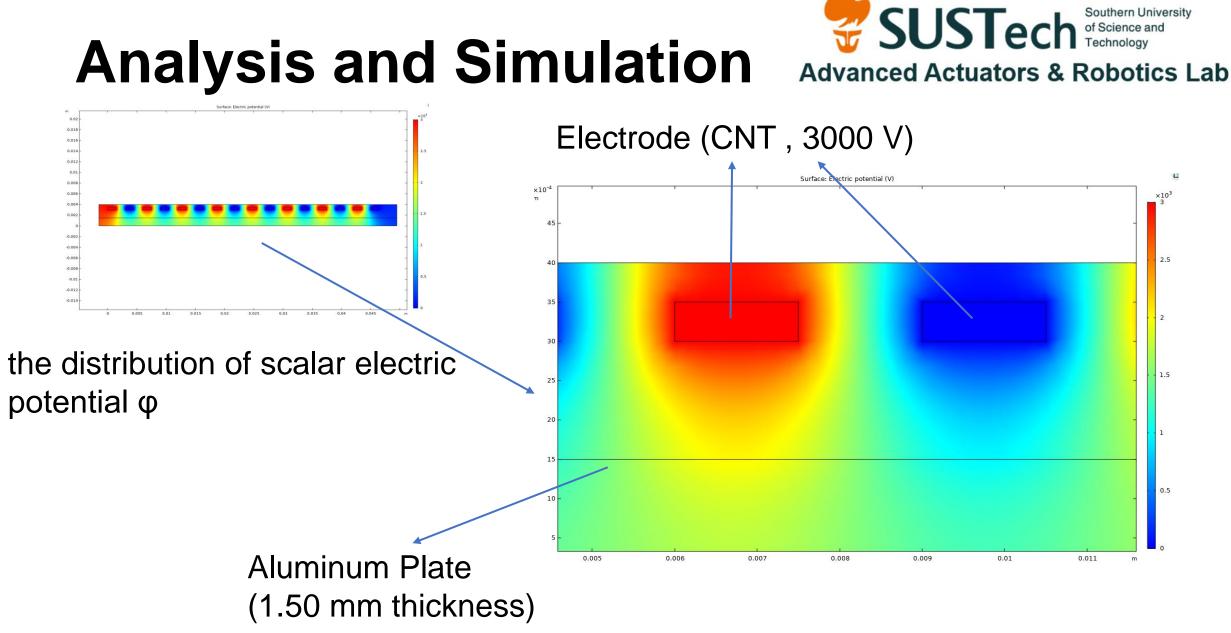
Results

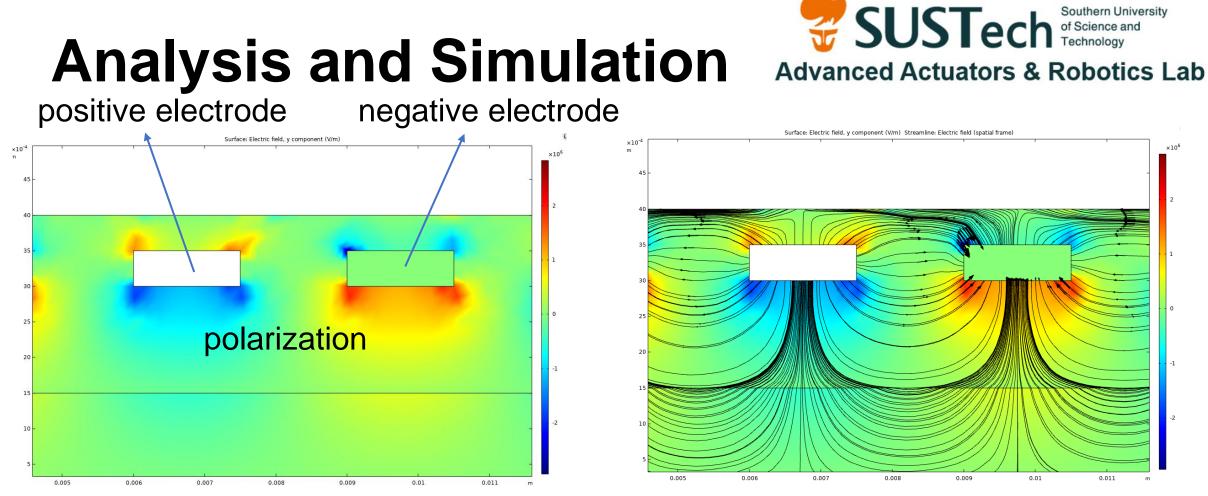


The bonding force (when voltage=2 kV \rightarrow 0, pressure=0)

Substrates	Bonding Force
paper	0.67 N
acrylic	5.41 N
copper	0.79 N
aluminum	1.56 N

- The final adhesion force = bonding force + electroadhesive force
- Electroadhesive force can introduces more bonding force (pressure sensitive).



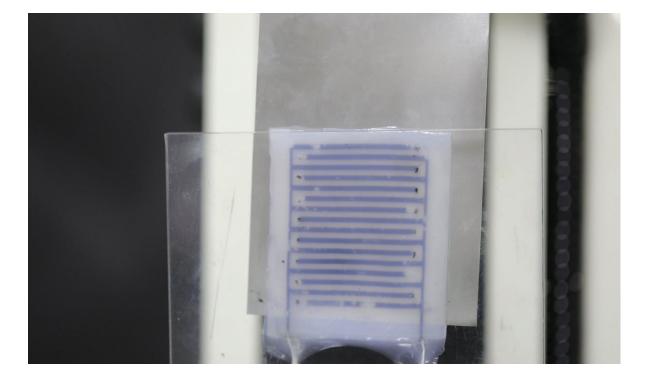


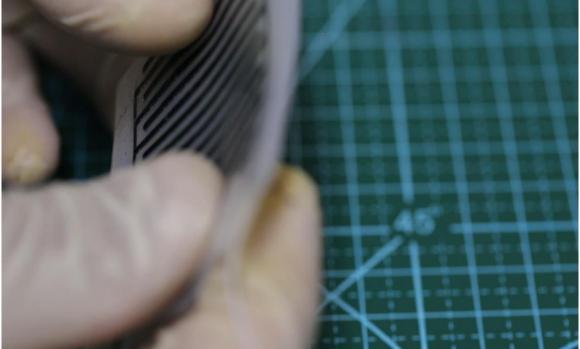
the distribution of electric field E in the definition area (with & without electric field line)

By simulation, $F_{sim} = 1.216 N$ By experiment, $F_{exp} = 3.49 - 1.56 = 1.93 N$

Self-healing





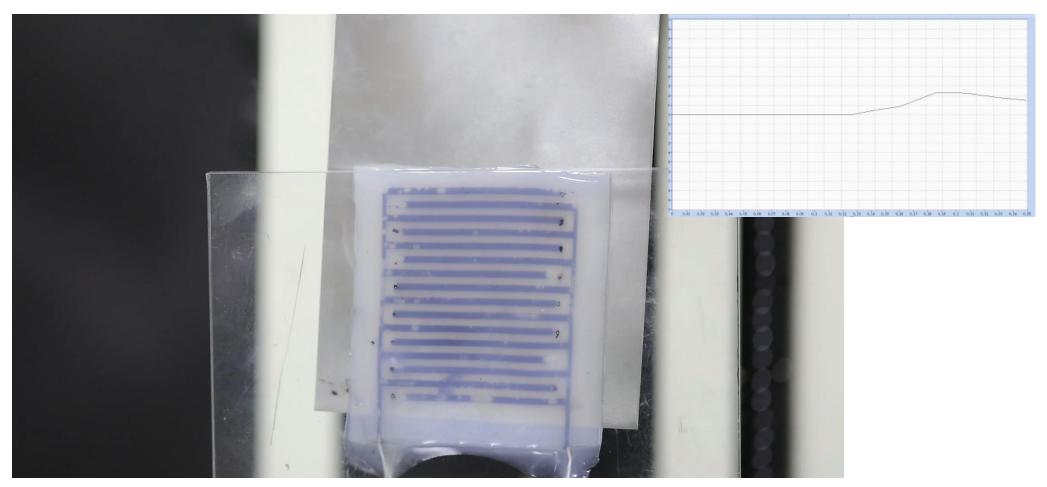


electrical breakdown

physically penetration

Self-healing

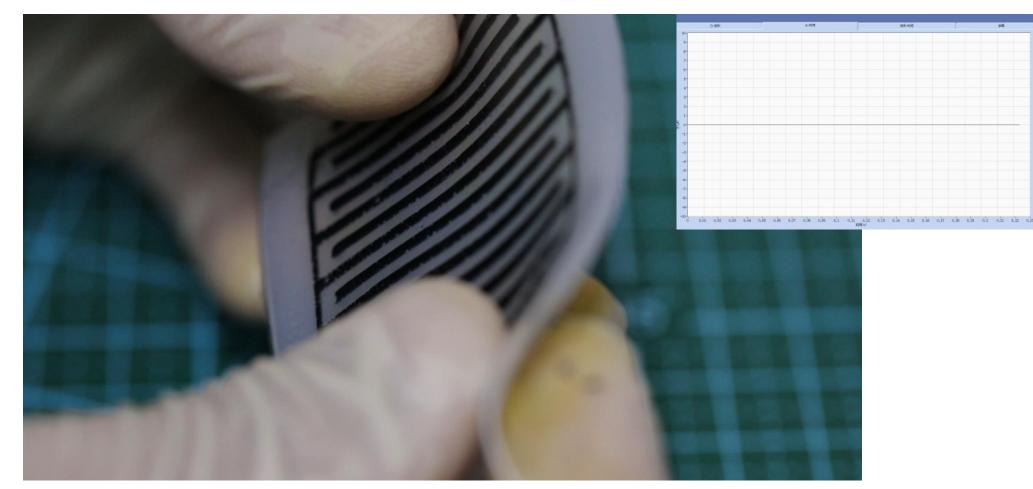




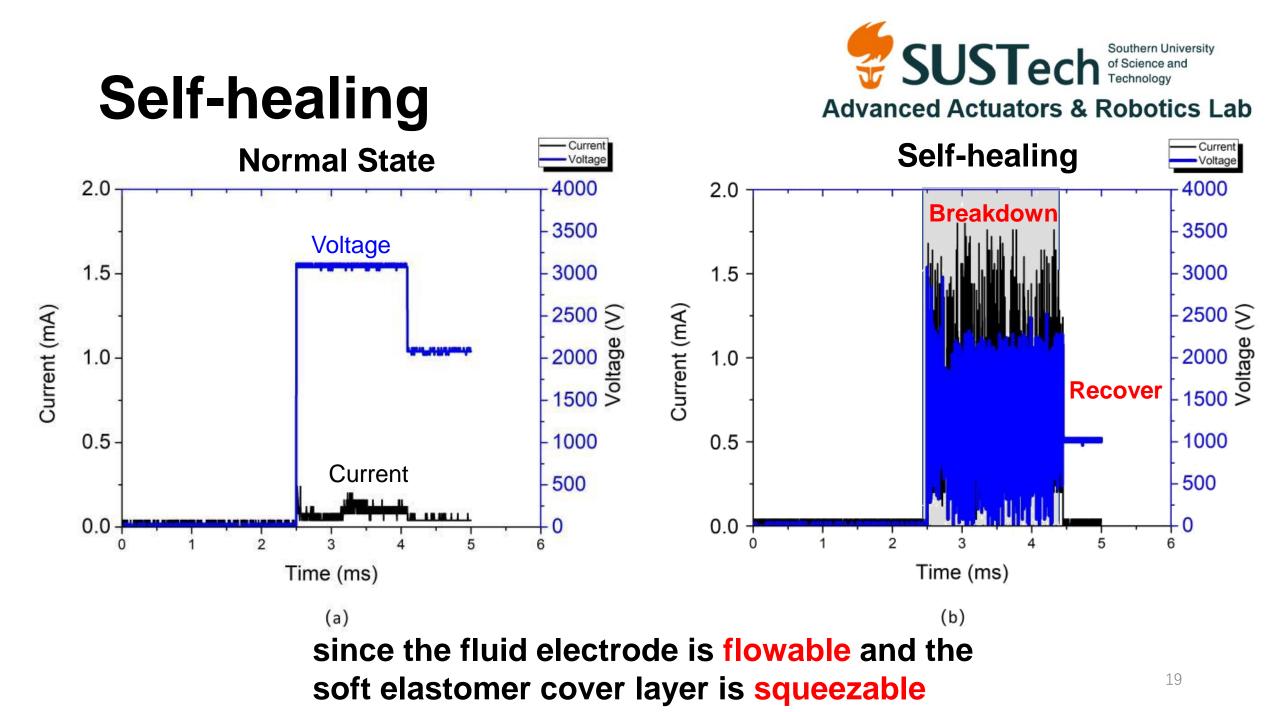
The adhesive pad can recover back and still work after the electrical breakdown (2500 - 3500 V) .

Self-healing





The adhesive pad can recover back and still work after the **physically penetration**.



Summary and discussion Advanced Actuators & Robotics Lab

- We propose a **flexible**, **stretchable** and **self-healing** electroadhesive pad.
- We describe a new simple method and material to fabricate stretchable and self-healing electroadhesive pads.
- After the electrical breakdown or physical penetration, the adhesive pad can recover back and still work, since the fluid electrode is flowable and the soft elastomer cover layer is squeezable.
- It can be used to improve the function of electroadhesive devices in existing applications, such as grippers, clutches, medical devices, and wallclimbing robots.
- It can also be used in **soft robotics**, where the traditional rigid metal pads are not stretchable and easy to be breakdown.

Thank you!

